

ON PARALLELOTOPE CONFIGURATION

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Abstract The parallelotope \mathcal{P} is a convex polytope which fills the space facet to facet by its translation copies without intersecting by inner points. A plane configuration is a system of p points and gstraight lines arranged in a plane in such a way that every point of the system is incident with a fixed number γ of straight lines of the system and every straight line of the system is incident with a fixed number π of points of the system. In this paper we examine the connection of 3-dimensional parallelotopes and point-line configurations in the plane and we generalize the concept of the parallelotope configuration (p-configuration).

1 Parallelotopes

The *parallelotope* \mathcal{P} is a convex polytope whose translated copies tile the space in a face to face manner. The centers of the parallelotopes form an *n*-dimensional lattice. In the plane there are two types of parallelotopes: parallelograms and centrally symmetric hexagons.

Parallelotopes were characterized by B. A. Venkov[15] and later P. McMullen[10] in the following way

Theorem 1. A polytope \mathcal{P} is a parallelotope if and only if

- *P* is centrally symmetric,
- each facet of \mathcal{P} is centrally symmetric, and
- the 2-dimensional orthogonal projection along any (n − 2)-face of P is either a parallelogram or a centrally symmetric hexagon.

The edges of the parallelogram and the centrally symmetric hexagon are projections of the facets of the parallelotope \mathcal{P} . These facets form a 4- or a 6-*belt*, respectively.

B. A. Venkov introduced the concept of the parallelotope of non-zero width in the direction of a k-subspace X^k . A parallelotope \mathcal{P} has non-zero width along X^k if the intersection $\mathcal{P} \cap (X^k + \mathbf{a})$ is either k-dimensional or empty for every translation vector \mathbf{a} . Denote by F(n-1) a facet of the parallelotope \mathcal{P} and by \mathbf{t} the lattice vector between the centers of the two nearest parallelotopes \mathcal{P} and \mathcal{Q} where \mathcal{P} and \mathcal{Q} have the common facet F(n-1). This lattice vector is called *relevant vector* of the facet F(n-1) by [7].

Theorem 2. (B. A. VENKOV [16]) Let \mathcal{P} be an n-dimensional parallelotope of non-zero width along X^k . Then the projection of \mathcal{P} along X^k is a parallelotope (of dimension n - k) and the lattice vectors \mathbf{t}_i related to the facets $F_i(n - 1)$ which are parallel to X^k generate an (n - k)-dimensional lattice spanning a space X^{n-k} which is transversal to X^k .

*Corresponding author. Tel. +36 76 516 438 E-mail address: vegh.attila@gamf.uni-neumann.hu By this theorem for k = n - 2 relevant vectors of a 4- or 6-belt span a 2-dimensional lattice, thus these relevant vectors are in a plane.

Consider the parallelotopes \mathcal{P} and \mathcal{Q} of dimension n. For k = 1 denote by $S(\mathbf{z})$ the segment X^k of the direction \mathbf{z} and of the length z. If there exists a direction \mathbf{z} for which $\mathcal{P} \oplus S(\mathbf{z}) = \mathcal{Q}$, where \oplus denotes the Minkowski sum, then \mathcal{P} is called the *contraction* of \mathcal{Q} and \mathcal{Q} is the *extraction* of \mathcal{P} .

Two parallelotopes in the plane were well-known already in the antiquity: the centrally symmetric hexagon (primitive) and the parallelogram (not primitive). E.S. FEDOROV in [5] described the 5 combinatorically different parallelotopes in 3-dimension among which the truncated octahedron is primitive and the others, namely the elongated octahedron, the rhombic dodecahedron, the hexagonal prism and the cube are not primitive. The following picture shows these 5 parallelotopes and their order indicates the way how you can get one from the other by extraction.



Figure 1. 3-dimensional parallelotopes

B.N. DELONE [1] found 51 different types of the 4-dimensional parallelotopes. M.I. SHTOGRIN gave the missing 52nd in [14]. 17 of these are zonotopes, the other 35 are the regular 24-cell and its Minkowski sum with some zonotopes. Three out of these types are primitive. S.S. RYSHKOV and E.P. BARANOWSKII [13] found 221 primitive 5-dimensional parallelotopes. One more was given by P. ENGEL and V. GRISHUKHIN [4]. P. ENGEL in [2] and [3] gave 179372 combinatorically different types of 5-dimensional parallelotopes.

In this paper we focus on 3-dimensional parallelotopes.

2 Configurations

A configuration is a system of p points and g straight lines arranged in a plane in such a way that every point of the system is incident with a fixed number γ of straight lines and every straight line of the system is incident with a fixed number π of points. Notation: (p_{γ}, g_{π}) .

The following relation must be true for every configuration:

$$p \cdot \gamma = g \cdot \pi. \tag{1}$$

The configurations in which the number of points is equal to the number of lines, i.e. for which p = g and consequently $\gamma = \pi$ are called symmetric or balanced configurations. For such a configuration we use the notation p_{γ} .



 (3_2) symmetric



 $(6_2, 4_3)$ nonsymmetric



The concept of the configuration may be generalized to higher dimensions, for instance to points and lines in the space. Point-line configurations can be realized in *n*-dimensional euclidean or projective space. For example the Desargues configuration have 10 points and 10 lines, every point lies on 3 lines and every lines contains 3 points, consequently this is a symmetric configuration (10_3) . The Reye configuration $(12_4, 16_3)$ is nonsymmetric.

Similarly, one can consider configurations of points and planes. In the Reye configuration there are 12 points and 12 planes each point of the configuration belongs to 6 planes, each plane contains 6 points, therefore as point-plane configuration (12_6) is symmetric.





Desargues configuration

Reye configuration

Figure 3. Configurations in space

Henceforth we are concerned with the connection of point-line configurations and parallelotopes.

3 Parallelotope configurations

Every *n*-polytope has a dual structure. It can be obtained by interchanging its vertices and facets, edges and (n-2)-dimensional faces, and so on, generally interchanging its (j-1)-dimensional elements and (n-j)-dimensional elements, preserving incidence between elements. The dual polytope of the polytope P is denoted by P^* . We use duality for parallelotopes. Facets of a parallelotope \mathcal{P} are centrally symmetric, thus we can define vertices of dual polytope P^* by centers of facets of the parallelotope \mathcal{P} . For example consider the blue truncated octahedron in the picture 4. The dual polytope is the red polytope, which is not a parallelotope.



Figure 4. Duality

Consider the dual polytope \mathcal{P}^* of a parallelotope \mathcal{P} . The parallelotope configuration or pconfiguration is a system of lines and points projected vertices and edges of the polytope \mathcal{P}^* from the center of the polytope \mathcal{P}^* to an (n-1)-dimensional hyperplane, which is parallel to a hyperplane containing the center of the parallelotope \mathcal{P} and not containing any vertex of the dual polytope \mathcal{P}^* . In this manner every parallelotope \mathcal{P} determines a p-configuration denoted by Π . A line of a p-configuration Π is called p-line. An example is presented on figure 5.



Figure 5. p-configuration

The notation of the p-configuration is

$$((p_1)_{\gamma_1}, (p_2)_{\gamma_2}, \dots, (p_k)_{\gamma_k}; ((g_1)_{\pi_1}, (g_2)_{\pi_2}, \dots, (g_l)_{\pi_l}),$$
(2)

where p_i is the number of points which belong to γ_i lines and g_i is the number of lines which contain π_i points. The sum of p_i is equal to the number of all points of the p-configuration and the sum of g_i is equal to the number of all lines of the p-configuration. Figure 6 shows p-configurations in the plane.



Figure 6. p-configuration in the plane

The geometric realizations of the p-configuration $(2_3, 4_2; 4_3, 1_2)$ and $(4_3, 3_2; 6_3)$ are different, but there is a projective transformation between the two geometric realizations.

4 Properties of the p-configuration

In this section we examine the properties of the p-configuration.

Theorem 3. Every *p*-line contains two or three points of the *p*-configuration Π . Every point of the *p*-configuration Π belongs to at least (n-1) straight lines, these lines generate a (n-1)-dimensional hyperplane.

Proof. The parallelotope \mathcal{P} contains 4- or 6-belt by theorem 1, thus the dual polytope \mathcal{P}^* has 4 or 6 vertices. On the other hand the parallelotope \mathcal{P} is centrally symmetric, and so is the dual polytope \mathcal{P}^* . The central projection of 2 opposite vertices is a point on the (n-1)-dimensional hyperplane. 4 or 6 vertices of the dual polytope \mathcal{P}^* are in a plane by theorem 2, causing that central projections of these vertices are on a line.

The proof of the second statement. A point of the p-configuration Π corresponds to a facet of the parallelotope \mathcal{P} and a line of the p-configuration Π corresponds to a belt of the parallelotope \mathcal{P} . A facet F_1 of the parallelotope \mathcal{P} is centrally symmetric, so the centrally symmetric image of a (n-2)-dimensional face G_1 of the parallelotope \mathcal{P} is an other (n-2)-dimensional face G_2 of the parallelotope \mathcal{P} . The face G_2 contains an other facet F_2 , this facet is centrally symmetric as well. The face G_3 is a centrally symmetric image of the face G_2 to the center of the facet F_2 . Repeating this procedure after 4 or 6 steps we get back the face G_1 by teorem 1, in this way a (n-2)-dimensional face G_1 of the parallelotope \mathcal{P} determines a belt of the parallelotope \mathcal{P} . There are at least 2 * (n-1) opposite (n-2)-dimensional faces on a facet F_i since it is a (n-1)-dimensional centrally symmetric polytope. On the hyperplane of the facet F_i the normal vectors of the (n-2)-dimensional faces G_i generate a (n-1)-dimensional hyperplane.

So facet F_i contains (n - 1) different belts and consequently a point of the p-configuration Π belongs to at least (n - 1) p-lines and these lines generate a (n - 1)-dimensional hyperplane.

Definition 1. The shadow boundary of a parallelotope \mathcal{P} in the direction \mathbf{z} consists of all boundary points \mathbf{x} of \mathcal{P} for which the line $\{\mathbf{x} + \lambda \mathbf{z} | \lambda \in \mathbb{R}\}$ is a support line of \mathcal{P} . (There is no point of the line $\{\mathbf{x} + \lambda \mathbf{z} | \lambda \in \mathbb{R}\}$ belonging to the interior of \mathcal{P}). It is denoted by $sh_{\mathbf{z}}(\mathcal{P})$.

It is well known that the shadow boundary of a convex polytope is the union of its several (n-1)and (n-2)-dimensional closed faces [9].

V. GRISHUKHIN [6] defined the z-cap of a parallelotope \mathcal{P} . A. MAGAZINOV and Á.G. HORVÁTH used this concept in [11], [7].

Definition 2. Let \mathcal{P} be an *n*-dimensional parallelotope and the vector \mathbf{z} be a free vector. The \mathbf{z} -cap $\operatorname{Cap}_{\mathbf{z}}(\mathcal{P})$ of a parallelotope \mathcal{P} consists of all the facets F of the parallelotope \mathcal{P} which satisfy the condition

$$\mathbf{z} \cdot \mathbf{n}(F) < 0, \tag{3}$$

where $\mathbf{n}(F)$ is the normal vector of the facet *F*.

Theorem 4. Both endpoints of every segments of the *p*-configuration Π are boundary points of the *p*-configuration Π .

Proof. Consider a direction z for which the shadow boundary $sh_z(\mathcal{P})$ is the union of only (n-2)-dimensional faces. It can easily be seen that projections of center points of facets F_i of the $\operatorname{Cap}_z(\mathcal{P})$ for which $sh_z(\mathcal{P}) \cap \operatorname{Cap}_z(\mathcal{P})$ is a (n-2)-dimensional face (that is facets F_i adjoin to shadow boundary) are the boundary points of a p-configuration Π .

Because of central symmetry every belt crosses the shadow boundary $sh_{\mathbf{z}}(\mathcal{P})$ in two (n-2)-dimensional faces. So two facets F_1 and F_2 of a belt are on a $\operatorname{Cap}_{\mathbf{z}}(\mathcal{P})$ for which $sh_{\mathbf{z}}(\mathcal{P}) \cap F_1$ and $sh_{\mathbf{z}}(\mathcal{P}) \cap F_2$ are (n-2)-dimensional faces.



Figure 7. Endpoints of segments

In this way both endpoints of segments corresponding to this belt are boundary points of a p-configuration Π .

Definition 3. Let *K* be a (n - k)-dimensional face of the parallelotope \mathcal{P} . Consider a *k*-dimensional hyperplane *H* that intersects the face *K* transversally. In a small neighborhood of the face *K* the section of the parallelotope tiling by the hyperplane *H* is called a fan of the face *K* and denoted by Fan(K).

B.N. DELONE [1] determined five possible combinatorial types of 3-dimensional fans which can be seen in figure 8.



Figure 8. 3-dimensional fans

Lemma 1. Let *K* be a (n-3)-dimensional face and G_i be a (n-2)-dimensional face and F_i be a facet of the parallelotope \mathcal{P} . Denote by $B(G_i)$ the set of facets F_i which form the belt of the (n-2)-dimensional face G_i . If $K \subseteq G_1$ and $K \subseteq G_2$ then $B(G_1) \cap B(G_2) \neq \emptyset$.

Proof. In the cases I, II, III if $K \subseteq G_1$ and $K \subseteq G_2$ then (n-2)-dimensional faces G_1 and G_2 determine a facet of the parallelotope \mathcal{P} , consequently the statement is true.

In the case IV for $G_1 = \langle A_1, K \rangle$ and $G_2 = \langle A_2, K \rangle$ the statement is similarly true.

The interesting case is for example $G_1 = \langle A_1, K \rangle$ and $G_2 = \langle A_3, K \rangle$. Let $\mathcal{P}_0 = \langle A_1, A_2, A_3, A_4, K \rangle$, $\mathcal{P}_1 = \langle A_1, A_2, A_5, A_6, K \rangle$, $\mathcal{P}_2 = \langle A_2, A_3, A_6, A_7, K \rangle$. In this situation the central symmetric image of the parallelotope \mathcal{P}_1 to the center C_1 of the facet $\langle A_1, A_2, K \rangle$ is the parallelotope \mathcal{P}_0 . Similarly the central symmetric image of the parallelotope \mathcal{P}_2 to the center C_2 of the facet $\langle A_2, A_3, K \rangle$ is the parallelotope \mathcal{P}_0 .

Facets $F_1 = \langle A_1, A_5, K \rangle$ and $F_2 = \langle A_3, A_7, K \rangle$ belong to a common (n-1)-dimnesional hyperplane H. The central symmetric image of the facet F_1 to the center C_1 is a facet F'_1 of the parallelotope \mathcal{P}_0 , which is parallel to the facet F_1 . The central symmetric image of the facet F_2 to the center C_2 is also a facet F'_2 of the parallelotope \mathcal{P}_0 , which is parallel to the facet F_1 . The central symmetric image of the facet F_2 , consequently $F'_1 \parallel F'_2$. Because facets F'_1 and F'_2 are in the same halfspace of the hyperplane H, so $F'_1 = F'_2 = F$. On the one hand $G_1 \subseteq F_1$ and $G_2 \subseteq F_2$ therefore $G'_1 \subseteq F$ and $G'_2 \subseteq F$ accordingly $\langle G'_1, G'_2 \rangle = F$. On the other hand $B(G_1) = B(G'_1)$ and $B(G_2) = B(G'_2)$ thus $F \in B(G'_1)$ and $F \in B(G'_2)$, consequently $F \in (B(G_1) \cap B(G_2))$.

In the case V choosing $A = A_5 = A_6 = A_7$ the proof is similar.

Theorem 5. The intersection of two uniplanar p-line is a point of the p-configuration Π .

Proof. A facet of the parallelotope \mathcal{P} corresponds to a point of the p-configuration Π . An (n-2)-dimensional face (belt) of the parallelotope \mathcal{P} corresponds to a line of the p-configuration Π . An (n-3)-dimensional face of the parallelotope \mathcal{P} corresponds to a plane of the p-configuration Π . The duality and the projection preserve the relation \subseteq . So if a plane contains two p-lines of the p-configuration Π , then an (n-3)-dimensional face of the parallelotope \mathcal{P} contains two corresponding (n-2)-dimensional faces of the parallelotope \mathcal{P} . By lemma 1 the intersection of two p-lines corresponding to two (n-2)-dimensional faces of the parallelotope \mathcal{P} is a point of the p-configuration Π which corresponds to the facet of the parallelotope \mathcal{P} .

Theorem 6. The convex hull of points of a p-configuration Π is a triangle in the plane.

Proof. In the plane the statement follows from theorem 5. Generally, we form the following conjecture.

Conjecture 1. The convex hull of points of a *p*-configuration is a (n-1)-dimensional simplex.

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